

Question

Suppose ϕ is a n -vector containing circuit design variables. Suppose $f(\phi)$ is a m -vector containing error functions in the form

$$W_U(F(\phi, \omega) - S_U(\omega))$$

and

$$-W_L(F(\phi, \omega) - S_L(\omega))$$

where S_U and S_L are upper and lower specifications on the circuit response F , respectively. W_U and W_L are weighting factors.

Suppose the quality of the circuit is measured by the generalized I_p function:

$$v(\phi) = H_p(f) = H_p(f(\phi)).$$

Suppose the circuit can be classified into 4 categories according to the following table.

category	criteria	retail price per circuit
high quality	If $v(\phi) \leq -1$	\$500
standard	If $-1 < v(\phi) \leq 0$	\$100
discounted	If $0 < v(\phi) \leq 1$	\$20
discarded	If $1 < v(\phi)$	-\$0.0

Consider the mass production of the circuit. Due to process variations and machine tolerances during production, some circuits maybe of high-quality while others may be standard or non-acceptable. Formulate a generalized I_p optimization to maximize the total income from the sales of the circuits.

Solution

Let $A = \$500.00$, $B = \$100.00$, $C = \$20.00$, $D = \$0.00$.

Let $\underline{\phi}^0$ be the nominal point. Let \underline{x} be a n -vector of random variables representing the random variation in $\underline{\phi}$. Consider K random samples $\underline{x}^{(k)}$, $k=1, 2, \dots, K$, and K circuits represented by

$$\underline{\phi}^{(k)} = \underline{\phi}^0 + \underline{x}^{(k)}, \quad k=1, 2, \dots, K \quad (1)$$

Consider generalized lp function

$$H_p < \underline{\mu}_A(\underline{\phi}^0) \quad (2)$$

where

$$\underline{\mu}_A = \begin{bmatrix} \alpha_A^{(1)} (v(\underline{\phi}^{(1)}) + 1) \\ \alpha_A^{(2)} (v(\underline{\phi}^{(2)}) + 1) \\ \vdots \\ \alpha_A^{(K)} (v(\underline{\phi}^{(K)}) + 1) \end{bmatrix} \quad (3)$$

(hint = " $v(\underline{\phi}) + 1$ " is derived from high-quality criteria $v(\underline{\phi}) \leq -1$, i.e., $v(\underline{\phi}) + 1 \leq 0$)

If we choose the weighting factors $\alpha_A^{(k)}$, $k=1, 2, \dots, K$ to be constant which equals $\alpha_A^{(k)} = \frac{1}{v(\underline{\phi}^{(k)}) + 1}$ at

the starting point of optimization, then

$$H_p^+(\underline{\mu}_A(\underline{\phi}^0)) \quad (4)$$

equals the number of non-high-quality circuits at starting point of optimization. If not all the K circuits are of high-quality, then

$$H_p(\underline{\mu}_A(\underline{\phi}^0)) = H_p^+(\underline{\mu}_A(\underline{\phi}^0)) \quad (5)$$

is an approximation of the number of non-high-quality circuits during optimization.

Similarly, we define K -vectors $\underline{\mu}_B$ and $\underline{\mu}_C$

whose k th element, $k=1, 2, \dots, K$, are $\alpha_B^{(k)} v(\underline{\phi}^{(k)})$

and $\alpha_C^{(k)} (v(\underline{\phi}^{(k)}) - 1)$, respectively,

$$\alpha_B^{(k)} = \frac{1}{v(\underline{\phi}^{(k)})} \quad (6)$$

$$\alpha_C^{(k)} = \frac{1}{v(\underline{\phi}^{(k)}) - 1} \quad (7)$$

are constant weighting factors calculated at starting point of optimization and kept unchanged during optimization.

$H_p(\underline{\mu}_B)$ approximates the number of discounted and failed circuits. $H_p(\underline{\mu}_c)$ approximates the number of failed circuits.

Total income from the sales of K circuits:

$$\begin{aligned} \text{income} &= A [K - H_p(\underline{\mu}_A)] + B [H_p(\underline{\mu}_A) - H_p(\underline{\mu}_B)] \\ &\quad + C [H_p(\underline{\mu}_B) - H_p(\underline{\mu}_c)] + D H_p(\underline{\mu}_c) \\ &= -(A-B) H_p(\underline{\mu}_A) - (B-C) H_p(\underline{\mu}_B) \\ &\quad - (C-D) H_p(\underline{\mu}_c) + A \cdot K \end{aligned} \quad (8)$$

The optimization problem for maximizing income is

$$\min_{\underline{\phi}^0} U(\underline{\phi}^0) \quad (9)$$

where

$$\begin{aligned} U(\underline{\phi}^0) &= (A-B) H_p(\underline{\mu}_A(\underline{\phi}^0)) + (B-C) H_p(\underline{\mu}_B(\underline{\phi}^0)) \\ &\quad + (C-D) H_p(\underline{\mu}_c(\underline{\phi}^0)) \\ &= 400 H_p(\underline{\mu}_A(\underline{\phi}^0)) + 180 \cdot H_p(\underline{\mu}_B(\underline{\phi}^0)) \\ &\quad + 20 \cdot H_p(\underline{\mu}_c(\underline{\phi}^0)). \end{aligned} \quad (10)$$

(Notice "A·K" in (8) is a constant and not included in (10))